<https://www.youtube.com/watch?v=2fbvgGQ6TuA>

Good bare bones demo

NOTE: The QMC5883L is different to the HMC5883L, why a lot of libs didn’t work

<https://www.instructables.com/Tilt-Compensated-Compass/>

Good for using an MPU to compensate for pitch and roll

Diagram

Description automatically generated

From: <https://www.instructables.com/Tutorial-to-Interface-HMC-5833L-With-Arduino-Uno/>